# Self Assignment Vector Spaces (Subspaces, Basis, Dimension)

#### 2024

## **Vector Spaces**

A vector space (or linear space) is a collection of objects called vectors, which can be added together and multiplied (scaled) by numbers, called scalars. Scalars are often real numbers ( $\mathbb{R}$ ) but can also come from other fields like complex numbers ( $\mathbb{C}$ ).

Formally, a vector space V over a field F (usually  $\mathbb{R}$  or  $\mathbb{C}$ ) satisfies the following properties: - \*\*Closure under addition\*\*: For any vectors  $u, v \in V$ ,  $u + v \in V$ . - \*\*Closure under scalar multiplication\*\*: For any scalar  $c \in F$  and any vector  $v \in V$ ,  $cv \in V$ . - \*\*Zero vector\*\*: There exists a zero vector  $0 \in V$  such that for any vector  $v \in V$ , v + 0 = v. - \*\*Additive inverses\*\*: For each  $v \in V$ , there is a vector  $-v \in V$  such that v + (-v) = 0. - \*\*Distributive and associative properties\*\* for vector addition and scalar multiplication.

#### Example 1: $\mathbb{R}^2$

The set of all 2-dimensional vectors with real components,  $\mathbb{R}^2$ , is an example of a vector space:

$$\mathbb{R}^2 = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} : x, y \in \mathbb{R} \right\}.$$

Vectors can be added, and they can be multiplied by scalars from  $\mathbb{R}$ .

$$\begin{pmatrix} 1\\2 \end{pmatrix} + \begin{pmatrix} 3\\4 \end{pmatrix} = \begin{pmatrix} 4\\6 \end{pmatrix}, \quad 2 \cdot \begin{pmatrix} 1\\2 \end{pmatrix} = \begin{pmatrix} 2\\4 \end{pmatrix}.$$

#### **Subspaces**

A subspace of a vector space V is a subset  $W \subseteq V$  that is itself a vector space under the same operations of vector addition and scalar multiplication.

For W to be a subspace, it must satisfy: 1. The zero vector of V is in W. 2. W is closed under vector addition. 3. W is closed under scalar multiplication.

## Example 2: Subspace of $\mathbb{R}^2$

The set of all vectors on a line through the origin in  $\mathbb{R}^2$  is a subspace. For example, the line y = 2x forms the subspace

$$W = \left\{ \begin{pmatrix} x \\ 2x \end{pmatrix} : x \in \mathbb{R} \right\}.$$

This is a subspace because it contains the zero vector  $\begin{pmatrix} 0\\ 0 \end{pmatrix}$ , and it is closed under both addition and scalar multiplication.

### Basis

A **basis** of a vector space V is a set of vectors in V that are linearly independent and span the entire vector space. This means every vector in V can be written as a linear combination of the basis vectors.

If  $B = \{v_1, v_2, \ldots, v_n\}$  is a basis for V, then for every vector  $v \in V$ , there are unique scalars  $a_1, a_2, \ldots, a_n$  such that:

$$v = a_1v_1 + a_2v_2 + \dots + a_nv_n.$$

## Example 3: Basis of $\mathbb{R}^2$

The standard basis for  $\mathbb{R}^2$  is:

$$B = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}.$$

Any vector in  $\mathbb{R}^2$  can be expressed as a linear combination of these two vectors. For example:

$$\begin{pmatrix} 3\\5 \end{pmatrix} = 3 \begin{pmatrix} 1\\0 \end{pmatrix} + 5 \begin{pmatrix} 0\\1 \end{pmatrix}.$$

## Dimension

The **dimension** of a vector space V is the number of vectors in any basis for V. If a vector space V has a basis consisting of n vectors, we say that V is n-dimensional, and we write:

$$\dim(V) = n.$$

## Example 4: Dimension of $\mathbb{R}^3$

The standard basis for  $\mathbb{R}^3$  consists of three vectors:

$$B = \left\{ \begin{pmatrix} 1\\0\\0 \end{pmatrix}, \begin{pmatrix} 0\\1\\0 \end{pmatrix}, \begin{pmatrix} 0\\0\\1 \end{pmatrix} \right\}.$$

Thus, the dimension of  $\mathbb{R}^3$  is 3.

$$\dim(\mathbb{R}^3) = 3.$$

## Linear Independence

A set of vectors  $\{v_1, v_2, \ldots, v_n\}$  in a vector space V is called **linearly independent** if the only solution to the equation:

$$a_1v_1 + a_2v_2 + \dots + a_nv_n = 0$$

is  $a_1 = a_2 = \cdots = a_n = 0$ . In other words, no vector in the set can be written as a linear combination of the others.

## Example 5: Linearly Independent Vectors in $\mathbb{R}^2$

The vectors  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  are linearly independent because the only solution to:

$$a_1 \begin{pmatrix} 1\\0 \end{pmatrix} + a_2 \begin{pmatrix} 0\\1 \end{pmatrix} = \begin{pmatrix} 0\\0 \end{pmatrix}$$

is  $a_1 = 0$  and  $a_2 = 0$ .

## Diagram: Visualizing a Subspace in $\mathbb{R}^2$



Figure 1: A subspace of  $\mathbb{R}^2$  represented by the line y = 2x. This subspace contains all scalar multiples of the vector  $\begin{pmatrix} 1\\ 2 \end{pmatrix}$ .